

## Script generated by TTT

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## 9 Functions

The definition of a function consists of:

- a **name** by which it can be called;
- a specification of the **formal parameters**;
- a possible **result type**;
- a **block of statements**.

In C, we have:

```
codeR f ρ = load c_f = start address of the code for f
```

⇒ Function names must be maintained within the address environment!

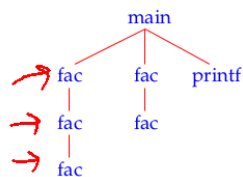
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### Example

```
int fac (int x) {  
    if (x ≤ 0) return 1;  
    else return x * fac(x - 1);  
}  
  
main () {  
    int n;  
    n = fac(2) + fac(1);  
    printf ("%d", n);  
}
```

At every point of execution, several **instances** (calls) of the same function may be active, i.e., have been started, but not yet completed.

The recursion tree of the example:



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### We conclude:

The **formal parameters** and **local variables** of the different calls of the same function (the **instances**) must be kept separate.

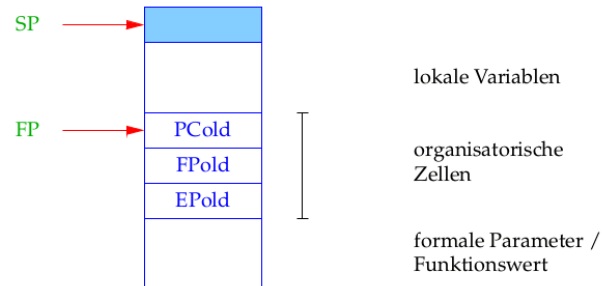
### Idea

Allocate a dedicated memory block for each call of a function.

In sequential programming languages, these memory blocks may be maintained on a stack. Therefore, they are also called **stack frames**.

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## 9.1 Memory Organization for Functions



FP  $\hat{=}$  **Frame Pointer**; points to the last **organizational cell** and is used for addressing the formal parameters and local variables.

71

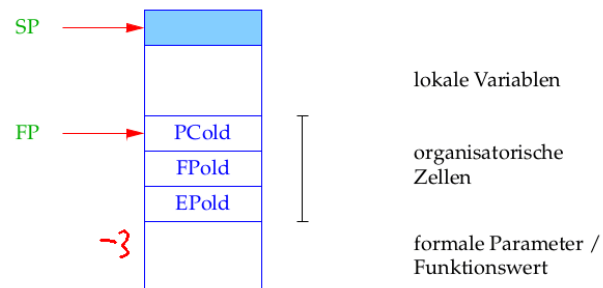
## Caveat

- The local variables receive relative addresses  $+1, +2, \dots$
- The formal parameters are placed **below** the organizational cells and therefore have **negative** addresses relative to FP :-))
- This organization is particularly well suited for function calls with **variable** number of arguments as, e.g., for **printf**.
- The memory block of parameters is recycled for storing the return value of the function :-))

**Simplification** The return value fits into a single memory cell.

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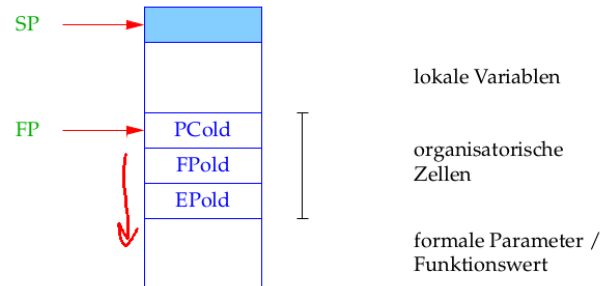
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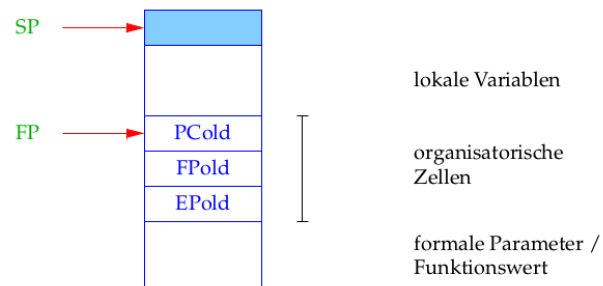
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### Tasks of a Translator for Functions:

- Generate code for the body of the function!
- Generate code for calls!

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## 9.2 Determining Address Environments

We distinguish two kinds of variables:

1. **global**/extern that are defined outside of functions;
2. **local**/intern/automatic (including formal parameters) which are defined inside functions.

$\implies$

The address environment  $\rho$  maps names onto pairs  $(tag, a) \in \{G, L\} \times \mathbb{Z}$ .

### Caveat

- In general, there are further refined grades of visibility of variables.
- Different parts of a program may be translated relative to different address environments!

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### Example

```
[0] in i;
    struct list {
        int info;
        struct list * next;
    } * l;

[1] int ith (struct list * x, int i) {
    if (i <= 1) return x ->info;
    else return ith (x ->next, i - 1);
}

[2] main () {
    int k;
    scanf ("%d", &i);
    scanlist (&l);
    printf ("\n\t%d\n", ith (i));
}
```

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### Address Environments Occurring in the Program:

#### [0] Outside of the Function Definitions:

```
 $\rho_0 :$ 
    i  $\mapsto$  (G, 1)
    l  $\mapsto$  (G, 2)
    ith  $\mapsto$  (G, _ith)
    main  $\mapsto$  (G, _main)
    ...
```

#### [1] Inside of ith:

```
 $\rho_1 :$ 
    i  $\mapsto$  (L, -4)
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1 int ith (struct list * x, int i) {
  if (i ≤ 1) return x → info;
  else return ith (x → next, i - 1);
}

2 main () {
  int k;
  scanf ("%d", &i);
  scanlist (&l);
  printf ("\n\t%d\n", ith (l,i));
}

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### Address Environments Occurring in the Program:

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```

#### 1 Inside of ith:

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```

### Caveat

- The actual parameters are evaluated from right to left !!
- The first parameter resides directly below the organizational cells :-)
- For a prototype  $\tau f(\tau_1 x_1, \dots, \tau_k x_k)$  we define:

$$x_1 \mapsto (L, -2 - |\tau_1|) \quad x_i \mapsto (L, -2 - |\tau_1| - \dots - |\tau_i|)$$

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#### 2 Inside of *main*:

```
 $\rho_2 :$ 
   $i \mapsto (G, 1)$ 
   $l \mapsto (G, 2)$ 
   $k \mapsto (L, 1)$ 
   $ith \mapsto (G, _ith)$ 
   $main \mapsto (G, _main)$ 
  ...
```

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### 9.3 Calling/Entering and Exiting/Leaving Functions

Assume that  $f$  is the current function, i.e., the caller, and  $f$  calls the function  $g$ , i.e., the callee.

The code for the call must be distributed between the caller and the callee.

The distribution can only be such that the code depending on information of the caller must be generated for the caller and likewise for the callee.

#### Caveat

The space requirements of the actual parameters is only known to the caller ...

$f$  calls  $g$

Actions when entering  $g$ :

- |  |         |                   |                   |
|--|---------|-------------------|-------------------|
| 1. Evaluating the actual parameters              | } mark  | } are part of $f$ |                   |
| 2. Saving of FP, EP                              |         |                   |                   |
| 3. Determining the start address of $g$          | } call  |                   | } are part of $g$ |
| 4. Setting of the new FP                         |         |                   |                   |
| 5. Saving PC and<br>Jump to the beginning of $g$ |         |                   |                   |
| 6. Setting of new EP                             | } enter |                   |                   |
| 7. Allocating of local variables                 |         | } alloc           |                   |

#### Actions when terminating the call:

- |   |          |
|---|----------|
| 1. Storing of the return value  | } return |
| 2. Restoring of the registers FP, EP, SP                              |          |
| 3. Jumping back into the code of $f$ , i.e.,<br>Restoration of the PC |          |
| 4. Popping the stack  | } slide  |

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Actions when terminating the call:

return  
var. par.

- |   |   |        |
|---|---|--------|
| 1. Storing of the return value  | } | return |
| 2. Restoring of the registers FP, EP                                  |   |        |
| 3. Jumping back into the code of $f$ , i.e.,<br>Restoration of the PC | } | slide  |
| 4. Popping the stack  |   |        |

Accordingly, we obtain for a call to a function with at least one parameter and one return value:

```

codeR g(e1, ..., en) ρ = codeR en ρ
...
codeR e1 ρ
mark
codeR g ρ
call
slide (m - 1)
    
```

where  $m$  is the size of the actual parameters.

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Remark

- Of every expression which is passed as a parameter, we determine the R-value  $\implies$  call-by-value passing of parameters.
- The function  $g$  may as well be denoted by an expression, dessen R-Wert die Anfangs-Adresse der aufzurufenden Funktion liefert ...

~~xx xg~~ = g

- Similar to declared arrays, function names are interpreted as **constant pointers** onto function code. Thus, the R-value of this pointer is the start address of the function.

- **Caveat!** For a variable `int (*)() g;` the two calls

`(*g)()`      und      `g()`

are equivalent! By means of **normalization**, the dereferencing of function pointers can be considered as redundant :-)

- During passing of parameters, these are copied.

Consequently,

`codeR f ρ` = `loadc (ρ f)`      *f* name of a function  
`codeR (*e) ρ` = `codeR e ρ`      *e* function pointer  
`codeR e ρ` = `codeL e ρ`  
                                  `move k`      *e* a structure of size *k*

where

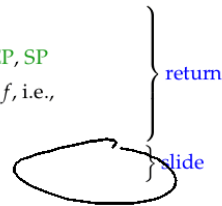
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`codeR g(e1, ..., en) ρ` = `codeR en ρ`  
 ...  
`codeR e1 ρ`  
`mark`  
`codeR g ρ`  
`call`  
`slide (m - 1)`

where *m* is the size of the actual parameters.

**Actions when terminating the call:**

1. Storing of the return value
2. Restoring of the registers `FP, EP, SP`
3. Jumping back into the code of *f*, i.e.,  
Restoration of the `PC`
4. Popping the stack



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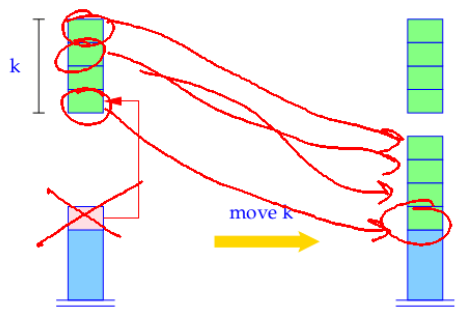
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```

for (i = k-1; i ≥ 0; i--)
  S[SP+i] = S[S[SP]+i];
SP = SP+k-1;

```

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The instruction `mark` saves the registers `FP` and `EP` onto the stack.



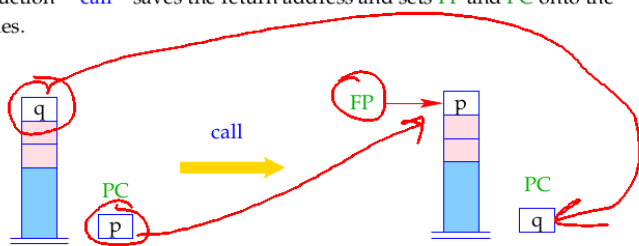
```

S[SP+1] = EP;
S[SP+2] = FP;
SP = SP + 2;

```

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The instruction `call` saves the return address and sets `FP` and `PC` onto the new values.



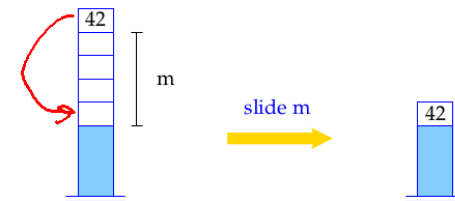
```

tmp = S[SP];
S[SP] = PC;
FP = SP;
PC = tmp;

```

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The instruction `slide` copies the return values into the correct memory cell:



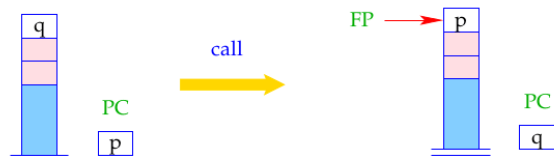
```

tmp = S[SP];
SP = SP-m;
S[SP] = tmp;

```

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The instruction `call` saves the return address and sets `FP` and `PC` onto the new values.



```
tmp = S[SP];
S[SP] = PC;
FP = SP;
PC = tmp;
```



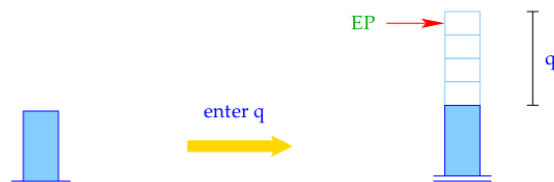
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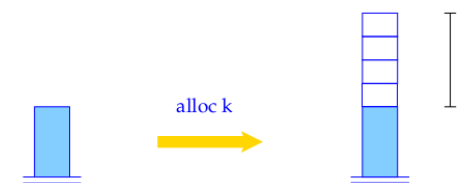
The instruction `enter q` sets the `EP` to the new value. If not enough space is available, program execution terminates.



```
EP = SP + q;
if (EP ≥ NP)
    Error ("Stack Overflow");
```

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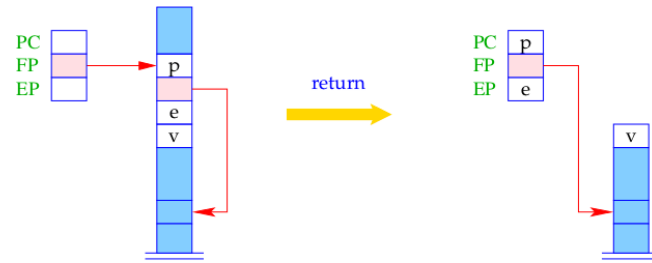
The instruction `alloc k` allocates memory for locals on the stack.



```
SP = SP + k;
```

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The instruction `return` pops the current stack frame. This means it restores the registers `PC`, `EP` and `FP` and returns the return value on top of the stack.



$PC = S[FP]; EP = S[FP-2];$   
if ( $EP \geq NP$ ) Error ("Stack Overflow");  
 $SP = FP-3; FP = S[SP+2];$