# Script generated by TTT

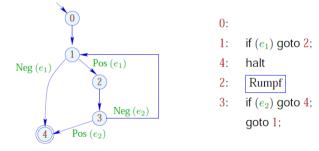
Title: Seidl: Programmoptimierung (05.12.2012)

Date: Wed Dec 05 09:31:53 CET 2012

Duration: 89:46 min

Pages: 49

# Example:



Bad: The loop body is jumped into :-(

2. Subproblem: Linearization

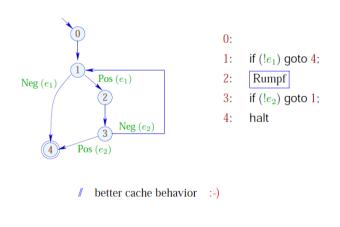
After optimization, the CFG must again be brought into a linearly arrangement of instructions :-)

Warning:

Not every linearization is equally efficient !!!

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# Example:



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#### Idea:

- Assign to each node a temperature!
- always jumps to
  - (1) nodes which have already been handled;
  - (2) colder nodes.
- Temperature ≈ nesting-depth

For the computation, we use the pre-dominator tree and strongly connected components  $\dots$ 

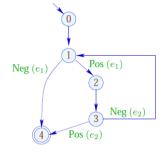
507

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Example:



0:

1: if  $(!e_1)$  goto 4;

2: Rumpf

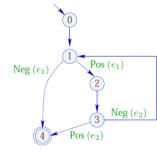
3: if  $(!e_2)$  goto 1;

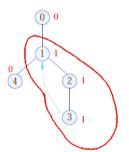
4: halt

// better cache behavior :-)

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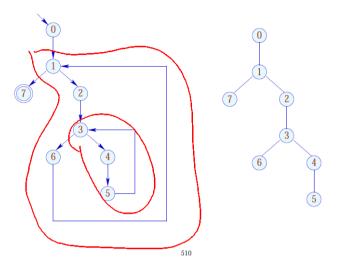
... in the Example:



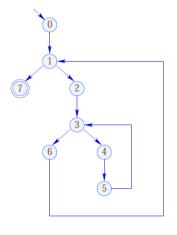


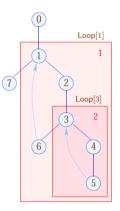
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# More Complicated Example:



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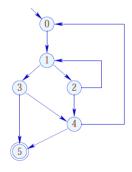


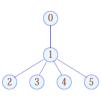


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Our definition of Loop implies that (detected) loops are necessarily nested :-)

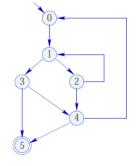
Is is also meaningful for do-while-loops with breaks ...

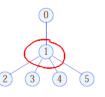




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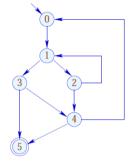
Is is also meaningful for do-while-loops with breaks  $\dots$ 

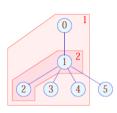




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Summary: The Approach

(1) For every node, determine a temperature;

(2) Pre-order-DFS over the CFG;

→ If an edge leads to a node we already have generated code for, then we insert a jump.

→ If a node has two successors with different temperature, then we insert a jump to the colder of the two.

→ If both successors are equally warm, then it does not matter ;-)

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### Summary: The Approach

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  - → If an edge leads to a node we already have generated code for, then we insert a jump.
  - → If a node has two successors with different temperature, then we insert a jump to the colder of the two.
  - $\rightarrow \hspace{0.4cm}$  If both successors are equally warm, then it does not matter ;-)

#### 2.3 Procedures

We extend our mini-programming language by procedures without parameters and procedure calls.

For that, we introduce a new statement:

f();

Every procedure f has a definition:

 $f() \{ stmt^* \}$ 

Additionally, we distinguish between global and local variables.

Program execution starts with the call of a procedure main ().

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# Example:

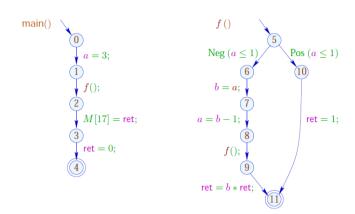
int a, ret; f () {
 main() {
 a=3;
 f();
 M[17]=ret;
 ret = 0;
}

int a, ret;
 f() {
 int b;
 if  $(a \le 1)$  {ret = 1; goto exit; }
 a=0;
 a=0;

Such programs can be represented by a set of CFGs: one for each procedure ...

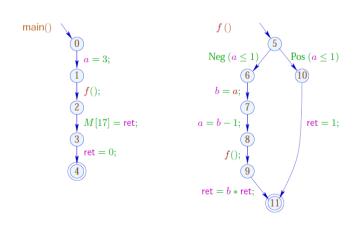
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### ... in the Example:



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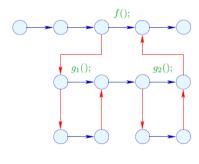
## ... in the Example:



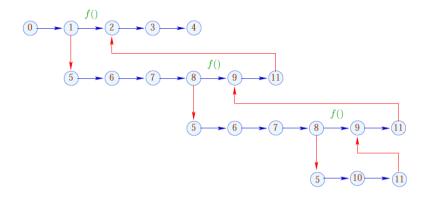
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In order to optimize such programs, we require an extended operational semantics ;-)

Program executions are no longer paths, but forests:



#### ... in the Example:



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The function [.] is extended to computation forests: w:

$$\llbracket w \rrbracket : (Vars \to \mathbb{Z}) \times (\mathbb{N} \to \mathbb{Z}) \to (Vars \to \mathbb{Z}) \times (\mathbb{N} \to \mathbb{Z})$$

For a call  $k = (\mathbf{u}, f(); \mathbf{v})$  we must:

determine the initial values for the locals:

enter 
$$\rho = \{x \mapsto 0 \mid x \in Locals\} \oplus (\rho|_{Globals})$$

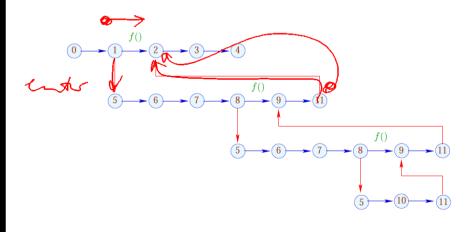
 ... combine the new values for the globals with the old values for the locals:

combine 
$$(\rho_1, \rho_2) = (\rho_1|_{Locals}) \oplus (\rho_2|_{Globals})$$

• ... evaluate the computation forest inbetween:

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... in the Example:



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For a call k = (u, f();, v) we must:



• determine the initial values for the locals:

enter 
$$\rho = \{x \mapsto b \mid x \in Locals\} \oplus (\rho|_{Globals})$$

 ... combine the new values for the globals with the old values for the locals:

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For a call k = (u, f(); v) we must:

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 ... combine the new values for the globals with the old values for the locals:

combine 
$$(\rho_1, \rho_2) = (\rho_1|_{Locals}) \oplus (\rho_2|_{Globals})$$

• ... evaluate the computation forest inbetween:

$$\llbracket k \ \langle w \rangle \rrbracket \ (\rho, \mu) \quad = \quad \text{let} \quad (\rho_1, \mu_1) = \llbracket w \rrbracket \ (\text{enter} \ \rho, \mu)$$
 
$$\text{in} \quad (\text{combine} \ (\rho, \rho_1), \mu_1)$$

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### Warning:

- In general,  $\llbracket w \rrbracket$  is only partially defined :-)
- Dedicated global/local variables  $a_i$ ,  $b_i$ , ret can be used to simulate specific calling conventions.
- The standard operational semantics relies on configurations which maintain a call stack.
- Computation forests are better suited for the construction of analyses and correctness proofs :-)
- It is an awkward (but useful) exercise to prove the equivalence of the two approaches ...

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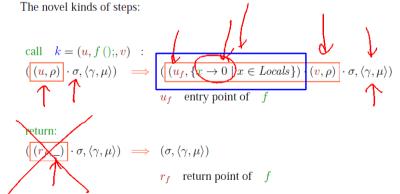
### Configurations:

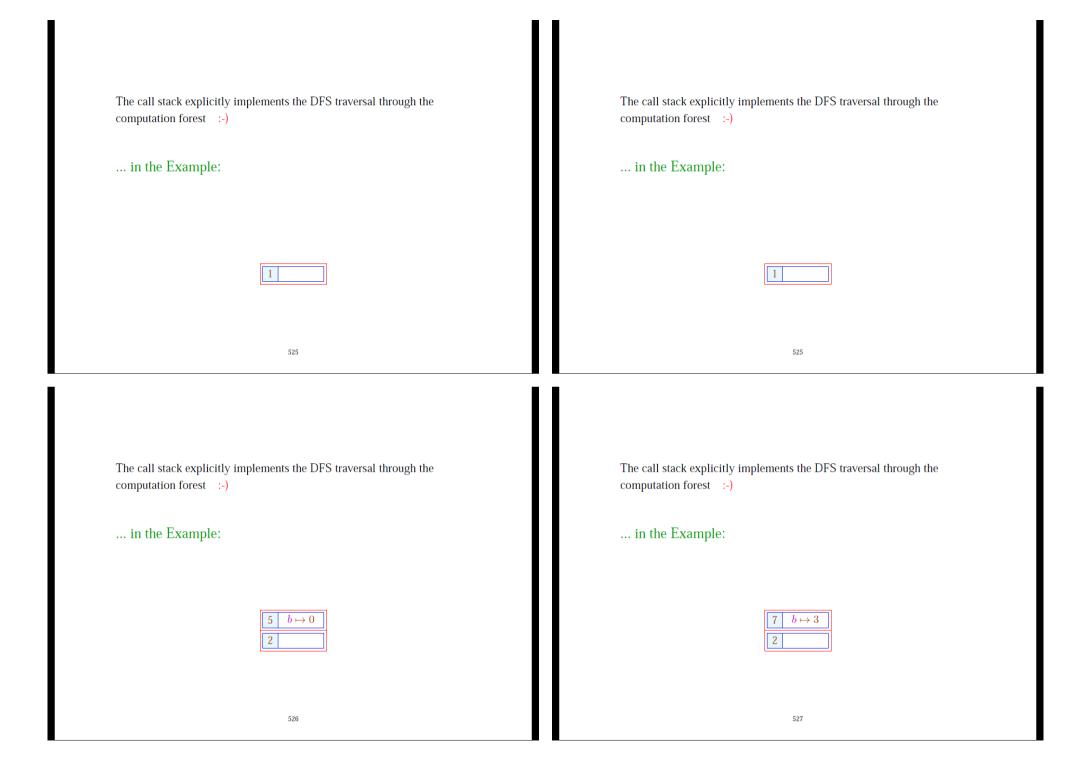
$$\begin{array}{lll} configuration & = & stack \times store \\ store & = & globals \times (\mathbb{N} \to \mathbb{Z}) \\ globals & = & (Globals \to \mathbb{Z}) \\ stack & = & frame \cdot frame^* \\ frame & = & point \times locals \\ locals & = & (Locals \to \mathbb{Z}) \\ \end{array}$$

A *frame* specifies the local state of computation inside a procedure call :-)

The leftmost frame corresponds to the current call.

Computation steps refer to the current call :-)





The call stack explicitly implements the DFS traversal through the computation forest  $\quad : \text{-})$ 

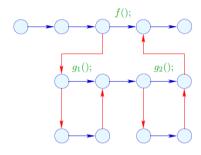
... in the Example:



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In order to optimize such programs, we require an extended operational semantics  $\,$  ;-)  $\,$ 

Program executions are no longer paths, but forests:



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The call stack explicitly implements the DFS traversal through the computation forest  $\quad : \text{-} )$ 

... in the Example:

$$\begin{array}{c|c}
5 & b \mapsto 0 \\
\hline
9 & b \mapsto 2 \\
\hline
9 & b \mapsto 3 \\
\hline
2 & \\
\end{array}$$

The call stack explicitly implements the DFS traversal through the computation forest :-)

... in the Example:

$$\begin{array}{c|c}
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2 & \\
\end{array}$$

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The call stack explicitly implements the DFS traversal through the computation forest :-)

... in the Example:

 $b \mapsto 2$  $b \mapsto 3$ 

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The call stack explicitly implements the DFS traversal through the computation forest :-)

... in the Example:

This operational semantics is quite realistic :-)

Costs for a Procedure Call:

**Before entering the body:** • Creating a stack frame;

- assigning of the parameters; Saving the registers;
- Saving the return address;
- Jump to the body.

**At procedure exit:** • Freeing the stack frame.

- Restoring the registers.
- Passing of the result.
- Return behind the call.

```
... quite expensive !!!
```

1. Idea: Inlining

Copy the procedure body at every call site !!!

Example:

```
abs() \{ max() \{
    a_2 = -a_1; if (a_1 < a_2) { ret = a_2; goto \underline{exit}; }
    max(); ret = a_1;
                 \_exit :
```

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```
... yields:
```

```
\begin{array}{c} abs\;()\;\;\{\\ a_2=-a_1;\\ & \text{ if }\;(a_1< a_2)\;\;\{\;\; \mathrm{ret}=a_2;\;\; \mathrm{goto}\;\; \_{exit};\;\;\}\\ & \text{ ret}=a_1;\\ & \_{exit}:\\ \end{cases}
```

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#### ... yields:

```
\begin{array}{c} abs \; () \; \; \{ \\ a_2 = -a_1; \\ \\ & \text{ if } \; (a_1 < a_2) \; \; \{ \; \, \text{ret} = a_2; \; \, \text{goto} \; \; \underline{exit}; \; \; \} \\ & \text{ ret} = a_1; \\ & \underline{-exit}: \\ \; \} \end{array}
```

## 1. Idea: Inlining

Copy the procedure body at every call site !!!

### Example:

```
abs\ ()\ \{ \ a_2 = -a_1; \ max\ ()\ \{ \ ret = a_2; \ goto\ \_exit; \ \} \ ret = a_1; \ \}
```

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#### Problems:

- The copied block may modify the locals of the calling procedure
- More general: Multiple use of local variable names may lead to errors.
- Multiple calls of a procedure may lead to code duplication :-((
- How can we handle recursion ???

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#### Detection of Recursion:

We construct the call-graph of the program.

In the Examples:





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## Call-Graph:

- The nodes are the procedures.
- An edge connexts g with h, whenever the body of g contains a call of h.

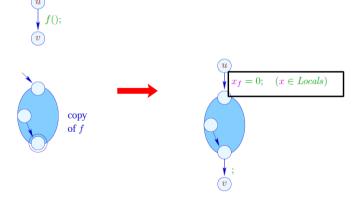
## Strategies for Inlining:

- Just copy nur leaf-procedures, i.e., procedures without further calls :-)
- Copy all non-recursive procedures!

... here, we consider just leaf-procedures ;-)

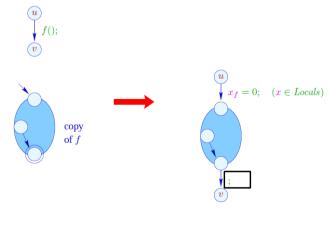
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### Transformation 9:



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#### Note:

- The Nop-edge can be eliminated if the  $\emph{stop}$ -node of f has no out-going edges ...
- The  $x_f$  are the copies of the locals of the procedure f.
- According to our semantics of procedure calls, these must be initialized with 0:-)

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#### 2. Idea:

#### Elimination of Tail Recursion

```
f() { int b;

if (a_2 \le 1) { ret = a_1; goto \_exit; }

b = a_1 \cdot a_2;

a_2 = a_2 - 1;

a_1 = b;

f();

\_exit :
```

After the procedure call, nothing in the body remains to be done.

... after having reset the locals to 0.