Script generated by TTT

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Type Definitions in C

The C grammar distinguishes typedef-name and identifier. Consider the following declarations:

Type Definitions in C

A type definition is a *synonym* for a type expression. In C they are introduced using the **typedef** keyword. Type definitions are useful

as abbreviation:

```
typedef struct { int x; int y; } point_t;
```

to construct recursive types:

Possible declaration in C:

```
typedef struct list list_t
struct list {
  int info;
  struct list* next;
}
struct list* head;
typedef struct list list_t
struct list {
  int info;
  list_t* next;
}
list t* head;
```

more readable:

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Type Definitions in C

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Problem:

- parser adds point_t to the table of types when the declaration is reduced
- parser state has at least one look-ahead token

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Type Definitions in C

The C grammar distinguishes typedef-name and identifier. Consider the following declarations:

Problem:

- parser adds point_t to the table of types when the declaration is reduced
- parser state has at least one look-ahead token
- the scanner has already read point_t in line two as identifier

Type Definitions in C: Solutions

Relevant C grammar:

Solution is difficult:

• try to fix the look-ahead inside the parser

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Solution is difficult:

- try to fix the look-ahead inside the parser
- add a rule to the grammar:
 typename → identifier

Type Definitions in C: Solutions

Relevant C grammar:

Solution is difficult:

- try to fix the look-ahead inside the parser
- add a rule to the grammar:
 S/R- & R/R- Conflicts!
 typename → identifier
- register type name earlier

Semantic Analysis

Chapter 3: Type Checking

Goal of Type Checking

In most mainstream (imperative / object oriented / functional) programming languages, variables and functions have a fixed type. for example: int, void*, struct { int x; int y; }.

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Types are useful to

```
manage memoryto avoid certain run-time errors
```

Goal of Type Checking

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Types are useful to

- manage memory
- to avoid certain run-time errors

In imperative and object-oriented programming languages a declaration has to specify a type. The compiler then checks for a type correct use of the declared entity.

Type Expressions

Types are given using type-*expressions*. The set of type expressions T contains:

- base types: int char, float void, ...
- type constructors that can be applied to other types

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- base types: int, char, float, void, ...
- type constructors that can be applied to other types

example for type constructors in C:

```
• structures: t_k t_k t_k t_k t_k t_k
```

- arrays t []
 - the size of an array can be specified
 - the variable to be declared is written between t and [n]
- functions: t (t_1, \ldots, t_k)
 - the variable to be declared is written between t and (t_1, \ldots, t_k)
 - ullet in ML function types are written as: $t_1 * \ldots * t_k o t$

Type Checking

Problem:

Given: A set of type declarations $\Gamma = \{t_1 \ x_1; \dots t_m \ x_m; \}$

Check: Can an expression e be given the type t?

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Example:

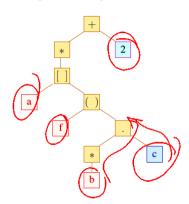
```
struct list { int info; struct list* next; };
int f(struct list* 1) { return 1; };
struct { struct list* c;}* b;
int* a[11];
```

Consider the expression:

```
*a[f(b->c)]+2;
```

Type Checking using the Syntax Tree

Check the expression *a[f(b->c)]+2:



Idea:

- traverse the syntax tree bottom-up
- for each identifier, we lookup its type in I
- constants such as 2 or 0.5 have a fixed type
- the types of the inner nodes of the tree are deduced using typing rules

Type Systems

Formally: consider *judgements* of the form:

 $\Gamma \vdash e : t$

(in the type environment Γ the expression e has type t)

Axioms:

Const: $\Gamma \vdash c$: t_c Var: $\Gamma \vdash x$: $\Gamma(x)$ $(t_c$ type of constant c) Variable)

Rules:

Ref: $\frac{\Gamma \vdash e : t}{\Gamma \vdash \& e : t*}$

Type Systems for C-like Languages

More rules for typing an expression:

 $\frac{\Gamma \vdash e_1 : t * \Gamma \vdash e_2 : \mathbf{int}}{\Gamma \vdash e_1[e_2] : t}$ Array:

 $\frac{\Gamma \vdash e_1 : t[] \quad \Gamma \vdash e_2 : \mathbf{int}}{\Gamma \vdash e_1[e_2] : t}$ Array:

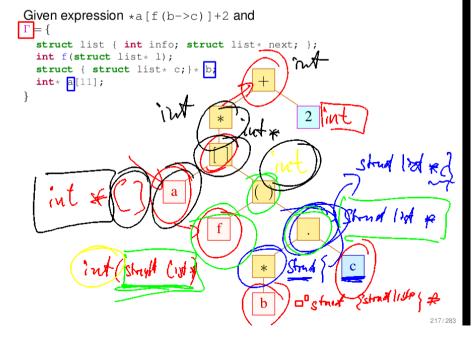
 $\frac{\Gamma \vdash e : \mathbf{struct} \{t_1 \ a_1; \dots t_m \ a_m;\}}{\Gamma \vdash e.a_i : t_i}$ Struct:

 $\frac{\Gamma \vdash e : t(t_1, \dots, t_m) \quad \Gamma \vdash e_1 : t_1 \dots \quad \Gamma \vdash e_m : t_m}{\Gamma \vdash e(e_1, \dots, e_m) : t}$ App:

Op:

Explicit Cast:

Example: Type Checking



Example: Type Checking

Equality of Types

Summary of Type Checking

- Choosing which rule to apply at an AST node is determined by the type of the child nodes
- determining the rule requires a check for → equality of types

type equality in C:

- struct A {} and struct B {} are considered to be different
 - → the compiler could re-order the fields of A and B independently (not allowed in C)
 - to extend an record A with more fields, it has to be embedded into another record:

```
struct B {
    struct A;
    int field_of_B;
} extension_of_A;
```

 after issuing typedef int C; the types C and int are the same

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Structural Type Equality

Alternative interpretation of type equality (*does not hold in C*):

semantically, two types t_1, t_2 can be considered as *equal* if they accept the same set of access paths.

Example:

```
struct list {
   int info;
   struct list* next;
}

struct list* next;

struct list1 {
   int info;
   struct {
   int info;
   struct list1* next;
   }* next;
```

Consider declarations struct list* 1 and struct list1* 1. Both allow

l->info l->next->info

but the two declarations of 1 have unequal types in C.

Algorithm for Testing Structural Equality

Idea:

- track a set of equivalence queries of type expressions
- if two types are syntactically equal, we stop and report success
- otherwise, reduce the equivalence query to a several equivalence queries on (hopefully) simpler type expressions

Suppose that recursive types were introduced using type definitions:

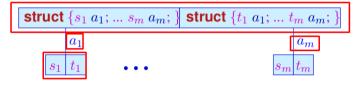
typedef A t

(we omit the Γ). Then define the following rules:

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Rules for Well-Typedness





Example:

struct {**int** info; A * next; } = B

We construct the following deduction tree:

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Example:

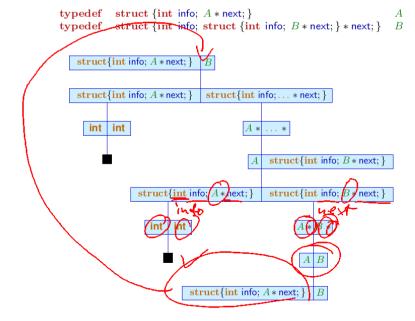
```
 \begin{array}{ll} \textbf{typedef} & \textbf{struct \{int info; } A*\mathsf{next;}\} \\ \textbf{typedef} & \textbf{struct \{int info; struct \{int info; } B*\mathsf{next;}\}*\mathsf{next;}\} \end{array}
```

We ask, for instance, if the following equality holds:

struct {**int** info;
$$A * next;$$
}

We construct the following deduction tree:

Proof for the Example:



Implementation

We implement a function that implements the equivalence query for two types by applying the deduction rules:

- if no deduction rule applies, then the two types are not equal
- if the deduction rule for expanding a type definition applies, the function is called recursively with a *potentially larger* type
- in case an equivalence query appears a second time, the types are equal by definition

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We implement a function that implements the equivalence query for two types by applying the deduction rules:

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Termination

- the set *D* of all declared types is finite
- there are no more than $|D|^2$ different equivalence queries
- repeated queries for the same inputs are automatically satisfied
- → termination is ensured

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Overloading and Coercion

Some operators such as + are *overloaded*:

- has several possible types
 for example: int +(int,int), float +(float, float)
 but also float* +(float*, int), int* +(int, int*)
- depending on the type, the operator + has a different implementation
- determining which implementation should be used is based on the type of the arguments only

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Coercion: allow the application of + to ${\tt int}$ and ${\tt float}$.

- → instead of defining + for all possible combinations of types, the arguments are automatically coerced
- conversion is usually done towards more general types i.e.
 5+0.5 has type float (since float ≥ int)
- coercion may generate code (e.g. converting int to float)

Subtypes

On the arithmetic basic types **char**, **int**, **long**, etc. there exists a rich *subtype* hierarchy

Subtypes

 $t_1 \le t_2$ means that the values of type t_1

- form a subset of the values of type t_2 ;
- ② can be converted into a value of type t_2 ;
- **1** fulfill the requirements of type t_2 ;
- $oldsymbol{0}$ are assignable to variables of type t2.

Subtypes

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Subtypes

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- \bigcirc fulfill the requirements of type t_2 ;
- $oldsymbol{\circ}$ are assignable to variables of type t2.

Example:

assign smaller type (fewer values) to larger type (more values)

$$t_1 \quad x;$$

$$t_2 \quad y;$$

$$y = x;$$

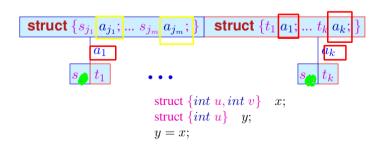
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Rules for Well-Typedness of Subtyping







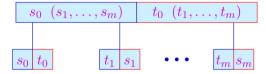
Rules and Examples for Subtyping



Examples:

```
 \begin{array}{lll} \textbf{struct} \ \{\textbf{int} \ a; \ \textbf{int} \ b; \} & \textbf{struct} \ \{\textbf{float} \ a; \} \\ \textbf{int} \ (\textbf{int}) & \textbf{float} \ (\textbf{float}) \\ \textbf{int} \ (\textbf{float}) & \textbf{float} \ (\textbf{int}) \\ \end{array}
```

Rules and Examples for Subtyping



Examples:

```
struct \{ int a; int b; \} \le struct \{ float a; \}
int (int)
                             float (float)
                         < float (int)
int (float)
```

Definition

Given two function types in subtype relation $s_0(s_1, ... s_n) \le t_0(t_1, ... t_n)$ then we have

- co-variance of the return type $s_0 < t_0$ and
- contra-variance of the arguments $s_i \geq t_i$ für $1 < i \leq n$

Subtypes: Application of Rules (I)

```
Check if S_1 \leq R_1:
                                  R_1 = struct {int a; R_1(R_1) f;}

S_1 = struct {int a; int b; S_1(S_1) f;}
                                 R_2 = \operatorname{struct} \left\{ \operatorname{int} a; R_2(S_2) f; \right\}
                                  S_2 = \operatorname{struct} \{ \operatorname{int} a; \operatorname{int} b; S_2(R_2) f; \}
                                                     S_1|R_1|
                               int
```

Subtypes: Application of Rules (II)

Check if $S_2 \leq S_1$:

```
R_1 = \mathbf{struct} \{ \mathbf{int} \ a; \ R_1(R_1) \ f; \}
                              R_1 = \text{struct {int } a, } R_1(R_1)f_1, f_2

S_1 = \text{struct {int } a; } \text{int } b S_1(S_1)f_2, f_3

R_2 = \text{struct {int } a; } R_2(S_2)f_3, f_3

S_2 = \text{struct {int } a; } \text{int } b S_2(R_2)f_3, f_3
                         |S_2|S_1
int
                                                S_2(R_2)
                                                                             S_1(S_1)
              int
                                                                              S_1 | R_2
                                                                                                                                    R_2 (S_2)
                                                       int int
                                                                                                       S_1(S_1)
```

Subtypes: Application of Rules (III)

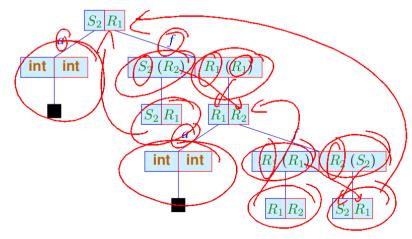
Check if $S_2 \leq R_1$:

```
= struct {int \underline{a}; R_1(R_1) \underline{f}; }
= struct {int a; int b; S_1(S_1) f; }
= struct {int a; R_2(S_2) f; }
= struct {int a; int b; S_2(R_2) f; }
```

 $S_1(S_1)$

 $R_1 (R_1)$

 $R_1 | \overline{S_1}$



Discussion

- for presentational purposes, proof trees are often abbreviated by omitting deductions within the tree
- structural sub-types are very powerful and can be quite intricate to understand
- Java generalizes records to objects/classes where a sub-class A inheriting form base class O is a subtype $A \leq O$
- subtype relations between classes must be explicitly declared
- inheritance ensures that all sub-classes contain all (visible) components of the super class
- a shadowed (overwritten) component in A must have a subtype of the the component in O
- Java does not allow argument subtyping for methods since it uses different signatures for overloading